

# JAPANESE INDUSTRIAL STANDARD

Translated and Published by Japanese Standards Association

 $JIS\ W\ 0141:2019$ 

(JUAV/JSA)

**Unmanned aircraft — Vocabulary** 

**ICS** 01.040.49; 49.020

Reference number: JIS W 0141: 2019 (E)

W 0141: 2019

Date of Establishment: 2019-10-21

Date of Public Notice in Official Gazette: 2019-10-21

Investigated by: Japanese Industrial Standards Committee

Standards Board for ISO area

JIS W 0141 : 2019, First English edition published in 2020-12

Translated and published by: Japanese Standards Association Mita MT Building, 3-13-12, Mita, Minato-ku, Tokyo, 108-0073 JAPAN

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Printed in Japan KK/HN

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#### Foreword

This Japanese Industrial Standard has been established by the Minister of Economy, Trade and Industry through deliberations at the Japanese Industrial Standards Committee according to the proposal for establishment of Japanese Industrial Standard submitted by Japan UAV Association (JUAV)/Japanese Standards Association (JSA) with a draft being attached, based on the provision of Article 12, paragraph (1) of the Industrial Standardization Act.

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## Unmanned aircraft — Vocabulary

JIS W 0141: 2019

#### 1 Scope

This Japanese Industrial Standard specifies main terms and definitions relating to unmanned aircraft.

#### 2 Classification

The classification of terms relating to unmanned aircraft shall be as follows.

- a) Classification
- b) Parts which constitute the system
- c) Design, function and performance criteria of the system
- d) Operation of the system

#### 3 Terms and definitions

Terms and definitions shall be as follows.

The corresponding English terms are also listed for reference.

- NOTE 1 When one term represents some concepts, the target field is shown in small letters in parentheses in the same line.
- NOTE 2 Since the term of "weight" is used in the sense of "mass" in the Civil Aeronautics Act, "weight" is used in the same way in this Standard.

#### a) Classification

No.	Japanese	Definition	English term
	term		(reference)
1001	無人航空機,	object which can be flown by manual control or au-	unmanned air-
	UAV	tomatic control among those such as an airplane,	craft,
		rotorcraft, aerodone and airship available for avia-	unmanned aer-
		tion which a person cannot board structurally	ial vehicle
1011	固定翼無人航	unmanned aircraft with a fixed wing surface, which	unmanned fixed
	空機	flies by the lift produced on the wing surface	wing aircraft,
			unmanned
			aeroplane
1021	回転翼無人航	unmanned aircraft which obtains the lift during	unmanned ro-
	空機	flight from the rotor	torcraft
1031	無人ヘリコプ	unmanned rotorcraft which obtains main lift and	unmanned hel-
	タ	propulsion power from two or less rotors which ro-	icopter
		tate around a nearly vertical axis	
1041	マルチロータ	unmanned rotorcraft which obtains main lift and	unmanned
	無人航空機	propulsion power from three or more rotors which	multi-rotor air-
		rotate around a nearly vertical axis	craft
-		It is also called multirotor or multicopter.	